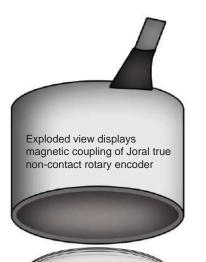
T COTTACT, DITCT, T OF 5



PATENTED NON-CONTACT TECHNOLOGY

Joral true non-contact position sensors utilize patented technology developed in-house by Joral, LLC. Rare earth magnets take the place of physical shaft coupling for true non-contact installation. Proven in mobile hydraulics Joral non-contact position sensing enables fast installation, extreme tolerances, and exceptional durability.

- True non-contact technology for extreme installation tolerances
- Watertight, totally encapsulated electronics (IP69K)
- Rugged-duty, bullet-proof hardware
- Standard housings as well as application specific pages (standard housings 18mm, 30mm, 38mm, 58mm)
- LED indicators provide live feedback for power and output



Measuring Micro Internal Magnet (Built into Sensor)

External Magnet (Mounted on Application)

A magnetic coupling is made between an *internal rotating* magnet (built into the position sensor) and an *external rotating* magnet (mounted on the application).

The non-contact sensor's *internal rotating magnet* couples with the *external rotating magnet* installed on the application.

The *external rotating magnet* (mounted on the application) and the *internal rotating magnet* (built into the encoder) magnetically couple and track as if they were physically connected.

AT-A-GLANCE SPECIFICATIONS

Installation Tolerances: GAP 0.5" (12mm) between application magnet

and encoder

AXIAL 0.10" (2.5mm) center alignment

PLANAR 30° tilt

Connection options include but not limited to: M12, M12 Pigtail, M8, Terminal Block, Flying Lead Cable, and various Deutsch connectors

Available Incremental Outputs:

- Quadrature Single Ended
- Quadrature Differential
- Step and Direction
- J1939 CAN Bus

Available Absolute Position Outputs:

- SSI (Synchronous serial interface)
- Analog or Current Output
- PWM (Pulse width modulation)
- J1939 CAN Bus
- Modicon MODBUS

ZERO POWER Multi-turn Capable Contact Joral for available Zero Power options







Hockey Puck™ & Prox Encoder™ Non-contact rotary position sensor HP58 / HP38 / PE30 / PE18

Non-contact; Brief / 2 of 3

NON-CONTACT **POSITION SENSORS**

TRUE NON-CONTACT POSITION SENSING

Joral true non-contact position sensors compensate for variations in distance, tilt, and off-center positioning of the magnet.

- Tolerances of 0.5" (12mm) gap, 30° tilt, and 0.1" (2.5mm) axial
- True non-contact limits mechanical wear
- Magnetic coupling makes for flexible installation





TOTALLY ENCAPSULATED ELECTRONICS

Automotive grade transparent potting compound protects electronic components and ensures a complete seal from external forces.

- Protection from shock, vibration, and direct impact
- IP69K protection for total moisture resistance
- Clear compound allows for LED indicators to be viewed

STANDARD PACKAGING STYLES

Joral non-contact senors available in prox-style and puck-style housings; 18mm & 30mm housings make for compact rotary position sensing.

- Small, standard, and convenient housing options
- Standard diameter and thread patterns
- Uses standard prox mounting hardware



ProxEncoder™ non-contact rotary position sensor displaying compact proximity housing



LED INDICATORS FOR LIVE FEEDBACK

LED indicators allow for constant monitoring of the sensor's operation.

- Power LED displays the status of sensor's power connections
- Channel and index LEDs relay the status of encoder output
- LEDs make for simple in-field troubleshooting and diagnostics

RUGGED-DUTY HARDWARE

Additional protection from electrical surges and mis-wiring are built into Joral non-contact rotary position sensors.

- Surge protectors for every input/output
- Reverse voltage protection provided against mis-wiring
- Internal auto-resettable fuse for extreme protection

STANDARD OPERATING CHARACTERISTICS **E**NCODER **O**UTPUT RESOLUTION **C**HARACTERISTICS **Quadrature Single Ended** 8 to 2048 PPR - Standard Resolutions: Format: Two channel quadrature A and B outputs Incremental Output 8, 10, 16, 20, 32, 40, 50, 64, 80, 100, 125, 128, with index pulse Z 200, 250, 256, 400, 500, 512, 1024, 2048 Driver: 7272 push-pull driver **Quadrature Differential** 8 to 2048 PPR - Standard Resolutions: Format: Two channel quadrature A and B outputs with index Incremental Output 8, 10, 16, 20, 32, 40, 50, 64, 80, 100, 125, 128, pulse Z and complementary outputs A', B', and Z' 200, 250, 256, 400, 500, 512, 1024, 2048 **Driver:** 7272 push-pull driver **Step and Direction** 16 to 512 PPR - Standard Resolutions: Format: One channel STEP output and one channel DIRECTION Incremental Output 16, 32, 64, 128, 256, 512 output with Index pulse Z **Driver:** 7272 push-pull driver Format: Clock and data output **SSI Absolute Position Output** 8192 Positions **Absolute Output** 0.0439 degrees per position **Driver:** Differential Output **PWM Absolute Position Output** Format: Pulse Width Modulation in 1 µsec increments 1024 or 2048 Positions **Absolute Output Driver:** 7272 push-pull driver **Analog Voltage Absolute Position** 0 to 5 VDC -OR- 4 to 20 mA Format: Output Voltage/Current proportional to 0-360 degrees **Absolute Output** 10 bit internal resolution Output Loading: 10mA max **1000 or 8192 Positions -** see J1939 output Format: Standard SAE J1939 CAN Bus - One message for status, J1939 CAN Bus Absolute or Incremental Output pages for message information one message for settings

ELECTRICAL SPECIFICATIONS

Input Power 6 to 30 VDC at approximately 60mA max, not including output loads

Electrical Protection Over-voltage, Reserve-voltage, Output short-circuit protected

LED Indicators Power and output channel status

Connection Types M8, M12, M12 on pigtail, Terminal block, Flying lead cable, Deutsch - 4 or 6 pin

ENVIRONMENTAL SPECIFICATIONS

Operating Temperature -30 to +80 degrees C

Storage Temperature -40 to +100 degrees C

Humidity 100%

Vibration 5 to 3000 Hz, 20g

Shock 400g 6msec (MIL STD 202)

Sensor Sealing IP69K (connector dependent) **Terminal block not IP rated**

MECHANICAL SPECIFICATIONS

Housing Diameter 18mm, 30mm, 38mm, and 58mm

Housing Material Aluminum, Stainless Steel, or Delrin™

Max Speed 3000 RPM

Model	Housing Diameter	WEIGHT	Неіднт	HEIGHT W/ M12
PE18	18mm	1 oz	1.87 inches (47.5mm)	N/A
PE30	30mm	1.5 oz	1.2 inches (30.5mm)	1.75 inches (44.5mm)
HP38	38mm	1.3 oz	0.69 inches (17.5mm)	N/A
HP58	58mm	2 oz	0.75 inches (19.1mm)	1.5 inches (38.1mm)

PE30 Prox Encoder™ non-contact rotary position sensor

- Extremely compact, J1939 capable
 - Shell body 1.2" (30.5mm) tall w/o connector
- Patented true non-contact position sensing
 - 0.5" (12mm) gap between sensor and application
 - 0.10" (2.5mm) center alignment
 - 30° planar tilt
- Totally sealed IP69K (connector dependent)
- LED indicators for power and output feedback
- Incremental or Absolute position
- Outputs: Quadrature, Step and Direction, SSI, PWM, Analog, Modicon MODBUS, & J1939 Can Bus



STANDARD OPERA	ATING CHARACTERIS	TICS
ELECTRICAL		Incremental 13 bit Quadrature w/ Single Ended Output A B Z
		Incremental 13 bit Quadrature w/ Differential Output A B Z & A' B' Z'
		J1939 13 bit @ 1000 positions (8192 positions max)
		PWM absolute position
		SSI absolute position @ 8192 positions
		Voltage Out / 5 VDC IN, 0-5 VDC OUT
		Voltage Out / 6-36 VDC IN, 0-5 VDC OUT
		Current Out / 0-24 VDC IN, 4-20 mA OUT
	Input Power	6 to 30 VDC at approx 60 mA max, not including output loads
	Electrical Protection	Over-voltage, reserve-voltage, output short-circuit protected
	LED Indicators	Power and output channels
	Connections	Terminal Plug, M8, M12, M12 Pigtail, Flying Lead Cable, Shielded Flying Lead, or Deutsch - 4 or 6 pin
	Resolution	0.3°
	Repeatability	0.30%
	Nonlinearity	<1%
MECHANICAL	Housing Diameter	30mm
MIECHANICAL	Housing Material	Aluminum or Stainless Steel (corrosion resistant)
	Housing Height	1.2" (30.5mm) body; 1.86" (47.2mm) w/ M12 connector
	Mounting	30mm thread (standard proximity switch thread style)
***	Weight	1.0 oz w/o mounting nuts; 2.2 oz w/ recommended mounting nuts
* Non-contact tolerances	Magnet / sensor gap*	Standard 0.5" (12mm) (Max w/ custom mag assembly up to 1" [30mm])
rated using MAGH-RING 1/4x20 magnet accessory.	Rated planer tilt / axial gap*	Planar 30° (Max 45°) / Axial 0.1" (2.5mm) (Max 0.16" [4mm])
177720 Hagnet accessory.	Speed	3000 RPM max
ENVIDONMENTAL	Operating Temperature	-30° to +80° C
ENVIRONMENTAL	Storage Temperature	-40° to +90° C
	Humidity	100%
	Shock	400g/6ms (MIL STD 202)
	Vibration	5 to 3000 Hz, 20g (MIL STD 202)
	Protection Class	IP69K (connection dependent)

General ordering guide found on next page (S2; I3/2)

Prox Encoder™ Non-contact rotary position sensor PE30 General Ordering Guide Non-contact; PE30 / 2 of 4

NON-CONTACT POSITION SENSORS

PE30 GENERAL ORDERING GUIDE

Build part number first by selecting **Housing Style** (code 1), **MagElec** (code 2), and **Connection** (code 3). Add **Special Codes** (code 4) to the end of the Joral part number. Refer to **'Special Part Number Information'** for explanation of modifiers.

Examples: PE30-A-1024-SEPP-M12-54 - Stainless Steel (PE30, modifier 54), M12 Connector (M12), 13 bit incremental quadrature @ 1024 PPR

PE30-A-1939-SC72-61 - Red aluminum (PE30), Extended thread (modifier 61), 72" Shielded cable (SC72)

PE30-V1-0-180-0-5-CW-C72 - Red aluminum (PE30), 72" Cable (C72), 0-5v out (V1) @ 0-180°, 0v to 5v out, clockwise direction (CW)

Code 1: Housing Style	Code 2: MagElec (Sensor Output)		Code 3: Connection		Code 4: Special Codes	
PE30			TRM	Pluggable Terminal block	51	Red Aluminum
PE30 red aluminum,		quadrature - A B Z	INS	Wire insertion terminal	53	Black Aluminum
For stainless steel housing add special code 54 to Joral P/N.			M8	M8 male	54	Stainless Steel
special code 34 to Joral P/N.			M12	M12 male	61	Extended Thread
Modifier Extended Thread:	A - 1939			M12 male on 18' pigtail	71	Roller
Special Code - 61			CXX		72	Spindle
Extended thread on PE30 housing increases available thread	B - PWM	Absolute position PWM		(enter XX as inches)	90	13 bit @ 8192 counts
length by 0.5" (12.7mm).	A - SSI1	Absolute position SSI @ 8192 positions	SCXX	Shielded cable (enter XX as inches)		per rotation (Typical J1939 option)
* More outputs and connection	V1	5 VDC IN, 0-5 VDC OUT	CSP	Cable with custom end		
options available, contact Joral if	V2	6-36 VDC IN, 0-5 VDC OUT	DE4	DT04 - 4 pin male Deutsch		
desired configuration is not listed	l1	0-24 VDC IN, 4-20 mA OUT	DE6	DT04 - 6 pin male Deutsch		

Special Part Number Information Review below code sections for important P/N build information

Code 1: Housing Style

- Modifier 54 PE30 Stainless steel housing for corrosive applications.
- **Modifier 61** Add 61 to P/N for extended thread. Standard shell length w/o M12 1.2" (30mm), Extended length w/o M12 1.7" (43mm). Code 61 adds 0.5" (12.7mm) length to thread for more access in threaded mounting.

Code 2: MagElec

(A - _ _ - SEPP) or (A - _ _ - DIPP)

- Enter Quadrature PPR in place of _ _ _ _
- A = 13 bit PPR
- Available 13 bit PPR: 0008, 0010, 0016, 0020, 0025, 0032, 0040, 0050, 0064, 0080, 0100, 0125, 0128, 0200, 0250, 0256, 0400, 0500, 1024, 2048

A - 1939

- Standard J1939 output is 1000 positions
- A = 13 bit
- MODIFIER 90 for 8192 positions (max resolution) add code 90 to end of PE30 P/N

V1, V2, and I1 (Analog MagElec P/N Guide)

- First select MagElec code (V1, V2 or I1) then Angle Range (A1-A2), Voltage Range (VR1-VR2) and Signal Direction (Clockwise [CW] or Counter [CCW])
- PART NUMBER FORMULA (MagElec)-(A1-A2)-(VR1-VR2)-(CW or CCW)
- EXACT V1, V2, and I1 EXAMPLES
 PE30 V1 0-360 0.5-4.5 CW C72
 PE30 V2 0-180 0-5 CCW DE4
 PE30 I1 180-270 4-20 CW M12

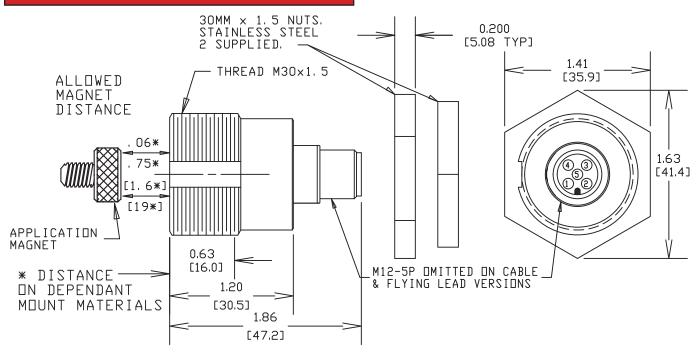
Code 3: Connections

- All Outputs, All Connections Connector exit back exit only (sensor epoxy side) for housing style PE30
- J1939 Output Addressing via varying value resistor in connection requires at least five conductors (M12, DE6 and Cables addressing compatible)
- All Outputs w/ Deutsch DE4 and DE6 connection Deutsch connectors add \$20 to PE30 list

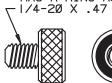
Prox Encoder™ Non-contact rotary position sensor PE30 Dimensions & General Pin-outs Non-contact; PE30 / 3 of 4

NON-CONTACT POSITION SENSORS

PE30 DIMENSIONS & GENERAL PIN OUTS



STANDARD MAGNET MAG-H-RING-ASSM.

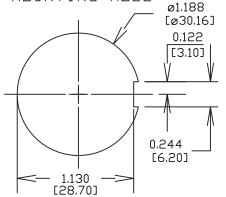




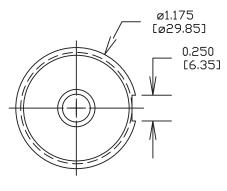
MAGNET NOTE:

STANDARD MAGNET INCLUDED AS ACCESSORY WITH PURCHASE OF NON-CONTACT SENSOR

RECOMMENDED MOUNTING HOLE



SENSOR FACE



DT04-4P MALE DT04-4P J1939 OUTPUT



FACE VIEW

1 = YEL = CAN HIGH 2 = GRN = CAN LOW

DT04-6P J1939 OUTPUT

GRN = CAN LOW

= +VDC (VIN)

= ADDRESS GROUND

WHT = ADDRESS PROG. RESISTOR

= COMMON/GROUND

1 = YEL = CAN HIGH

3 = RED = +VDC (VIN) 4 = BLK = COMMON/GROUND

M12-5P MALE FACE VIEW



M12-5P/CABLE/FLYING LEAD QUADRATURE OUTPUT

1 = BRN = +VDC (VIN) 2 = WHT = CHANNEL B 3 = BLUE = COMMON/GROUND

4 = BLK = CHANNEL A 5 = GRY = CHANNEL Z

M12-5P AND 5 CONDUCTOR CABLE J1939 OUTPUT

1 = BRN = +VDC (VIN) 2 = WHT = CAN HIGH

3 = BLUE = COMMON/GROUND 4 = BLK = CAN LOW

5 = GRY = OPTIONAL ADDRESS PROGRAMMING RESISTOR

Dimensions informative only For most recent dimensions please consult factory

=

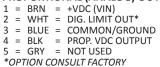
= BIK

4 = BLK

3 = RFD

5 =

M12-5P/CABLE/FLYING LEAD PROPORTIONAL (ANALOG) OUTPUT

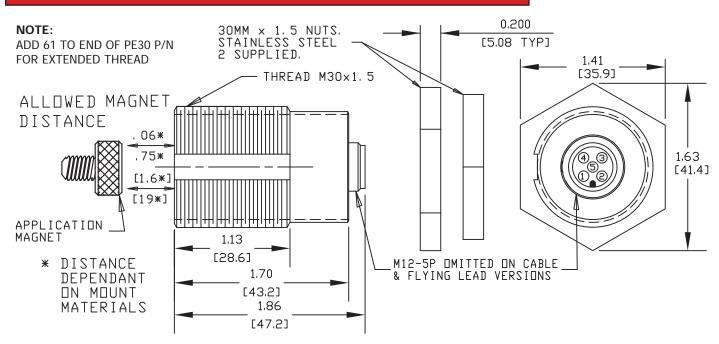




Prox Encoder™ Non-contact rotary position sensor PE30 Dimensions & General Pin-outs Non-contact; PE30 / 4 of 4

NON-CONTACT **POSITION SENSORS**

PE30 EXTENDED THREAD DIMENSIONS & GENERAL PIN OUTS







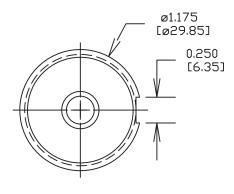
MAGNET NOTE:

STANDARD MAGNET INCLUDED AS ACCESSORY WITH PURCHASE OF NON-CONTACT SENSOR

MUUNTING HULF ø1.188 [ø30.16] 0.122 [3.10] 0.244 [6.20]

RECOMMENDED

SENSOR FACE



DT04-4P MALE DT04-4P J1939 OUTPUT



1 = YEL = CAN HIGH = GRN = CAN LOW

= RED = +VDC (VIN) = COMMON/GROUND



DT04-6P J1939 OUTPUT 1 = YEL = CAN HIGH 2 = GRN = CAN LOW

= +VDC (VIN) 3 = RFD 4 = BLK= ADDRESS GROUND WHT = ADDRESS PROG. RESISTOR =

5 = COMMON/GROUND = BLK

M12-5P MALE M12-5P/CABLE/FLYING LEAD **FACE VIEW** QUADRATURE OUTPUT



1.130 [28.70]

> 1 = BRN = +VDC (VIN)

2 = WHT = CHANNEL B 3 = BLUE = COMMON/GROUND 4 = BLK CHANNEL A = GRY = CHANNEL Z

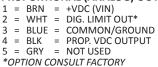
M12-5P AND 5 CONDUCTOR **CABLE J1939 OUTPUT**

1 = BRN = +VDC (VIN) 2 = WHT = CAN HIGH

3 = BLUE = COMMON/GROUND 4 = BIKCANTOW

OPTIONAL ADDRESS 5 = GRYPROGRAMMING RESISTOR

M12-5P/CABLE/FLYING LEAD PROPORTIONAL (ANALOG) OUTPUT



Dimensions informative only For most recent dimensions please consult factory

HP38 Hockey Puck[™] non-contact rotary position sensor

- OEM driven solution with minimum order quantities
- Compact bare bones non-contact rotary encoder
 - Body only 0.69" (17.5mm) tall
- Patented true non-contact position sensing
 - 0.5" (12mm) gap between sensor and application
 - 0.10" (2.5mm) center alignment
 - 30° planar tilt
- Totally sealed IP69K (connector dependent)
- LED indicators for power and output feedback
- Outputs: Quadrature, SSI, Analog, & J1939 Can Bus



STANDARD OPERATING CHARACTERISTICS

ELECTRICAL	Outputs	B - <i>[PPR]</i> - SEPP	Incremental 10 bit Quadrature w/ Single Ended Output A B Z
ELECTRICAL		B - 1939	J1939 10 bit @ 512 positions
		B - PWM	PWM absolute position
		B - SSI1	SSI absolute position @ 512 positions
		V1	Voltage Out / 5 VDC IN, 0-5 VDC OUT
		V2	Voltage Out / 6-36 VDC IN, 0-5 VDC OUT
	Input Powe	er	6 to 30 VDC at approx 60 mA max, not including output loads
	Electrical P	rotection	Over-voltage, reserve-voltage, output short-circuit protected
	LED Indica	tors	Power and output channels
	Connection	ns	M8, M12 Pigtail, Terminal Block, Flying Lead Cable, or Deutsch (4 or 6 pin)
	Resolution		0.3°
_	Repeatabil	ity	0.30%
	Nonlineari		<1%
MECHANICAL Housing Diameter Housing Material			38mm
			Black Delrin™ (standard)
_	Housing H	eight	0.69" (17.5mm) body
_	Mounting		32mm (.884) spacing w/ 4mm diameter screws
* Non-contact tolerances	Weight		1.3 oz
rated using MAGH-RING		ensor gap*	Standard 0.5" (12mm) (Max w/ custom mag assembly up to 1" [30mm])
1/4x20 magnet accessory.		er tilt / axial gap*	Planar 30° (Max 45°) / Axial 0.1" (2.5mm) (Max 0.16" [4mm])
	Speed		3000 RPM max
ENVIRONMENTAL		Temperature	-30° to +80° C
ENVINORMENTAL	Storage Te	mperature	-40° to +90° C
	Humidity		100%
	Shock		400g/6ms (MIL STD 202)
	Vibration		5 to 3000 Hz, 20g (MIL STD 202)
	Protection	Class	IP69K (connection dependent)

General ordering guide found on next page (\$2; I4/2)

Hockey Puck™ Non-contact rotary position sensor HP38 General Ordering Guide Non-contact; HP38 / 2 of 3

NON-CONTACT POSITION SENSORS

HP38 GENERAL ORDERING GUIDE

Build part number first by selecting **Housing Style** (code 1), **MagElec** (code 2), and **Connection** (code 3). Add **Special Codes** (code 4) to the end of the Joral part number. Refer to **'Special Part Number Information'** for explanation of modifiers.

Examples: HP38-B-0256-SEPP-M12P - Black Delrin™ (HP38), M12 pigtail (M12P), 10 bit incremental quadrature @ 256 ppr

HP38-B-1939-SC72 - Black Delrin[™] (HP38), 72" Shielded cable, 10 bit J1939 @ 512 positions

HP38-V1-0-360-0.5-4.5-CW-C72 - Black Delrin™ (HP38), 72" Cable (SC72), 0-5v Voltage Out (V1) @ 0-360°, 0.5-4.5v out, clockwise signal

Code 1: Housing Style	Code 2: MagElec (Sensor Output)		Code 3: Connection		Code 4: Special Codes	
HP38	B SEPP	10 bit single ended quadrature - A B Z	TRM	Pluggable Terminal block	31	Side Exit (housing wall)
HP38 material black Delrin™,			M8	M8 male	33	Back Exit (epoxy side)
connector orientation SIDE EXIT. For REAR EXIT connector on HP38	B - 1939	10 bit J1939	M12P	M12 male on 18' pigtail	71	Roller
add code 33 to end of P/N.		@ 512 positions	CXX	Flying lead cable	72	Spindle
	B - SSI1 Absolute position SSI			(enter XX as inches)		
		@ 512 positions	SCXX			
	B - PWM	PWM absolute position		(enter XX as inches)		
* More outputs and connection	V1	5 VDC IN, 0-5 VDC OUT	DE4	DT04 - 4 pin male Deutsch		
options available, contact Joral if	V2	6-36 VDC IN, 0-5 VDC OUT	DE6	DT04 - 6 pin male Deutsch		
desired configuration is not listed						

Special Part Number Information Review below code sections for important P/N build information

Code 1: Housing Style

- Modifier 33 For BACK EXIT connector orientation on HP38 add 33 to end of Joral P/N
- HP38 Handles ALL back exit and CABLE ONLY side exit connections

Code 2: MagElec

(B - _ _ - SEPP)

- Enter Quadrature PPR in place of _ _ _
- B = 10 bit PPR
- Available 10 bit PPR: 0032, 0064, 0128, 0256

B - 1939

- 10 bit J1939 output is 512 positions
- B = 10 bit

V1, V2, and I1 (Analog MagElec P/N Guide)

- First select MagElec code (V1, V2 or I1) then Angle Range (A1-A2), Voltage Range (VR1-VR2) and Signal Direction (Clockwise [CW] or Counter [CCW])
- PART NUMBER FORMULA (MagElec)-(A1-A2)-(VR1-VR2)-(CW or CCW)
- EXACT V1, V2, and I1 EXAMPLES
 HP38 V1 0-360 0.5-4.5 CW C72
 HP38 V2 0-180 0-5 CCW C72

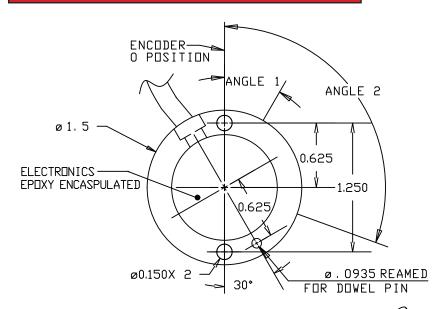
HP38 - I1 - 180-270 - 4-20 - CW - C72

Code 3: Connections

- All Outputs, All Connections Standard connection orientation SIDE EXIT. For BACK EXIT connector on HP38 add 33 to end of Joral HP38 P/N
- J1939 Output Addressing via varying value resistor in connection requires at least five conductors (M12, DE6 and Cables addressing compatible)
- All Outputs w/ Deutsch DE4 and DE6 connection Deutsch connectors add \$20 to HP38 list

Non-contact; HP38 / 3 of 3

HP38 DIMENSIONS & GENERAL PIN OUTS

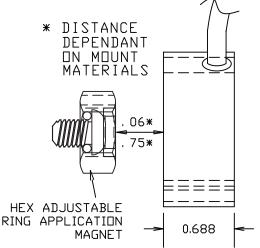


HOUSING/INSTALL NOTES:

MAGNET MOUNT MATERIALS MUST HAVE Ø1.0 [25.4] HOLE CENTERED ON SENSOR CENTERLINE

NON-MAGNETIC MOUNT MATERIAL, MAY BE SOLID

MOUNT WITH 316 STAINLESS STEEL 4-40 SCREWS



STANDARD MAGNET MAG-H-RING-ASSM. - 1/4-20 X .47





MAGNET NOTE:

STANDARD MAGNET INCLUDED AS ACCESSORY WITH PURCHASE OF NON-CONTACT SENSOR

V1, V2, I1

HEX ADJUSTABLE MAGNET DETAIL (FACE VIEW)



HEX ADJUSTABLE MAGNET NOTE:

ADJUSTABLE RING MAGNET INCLUDED AS ACCESSORY WITH PURCHASE OF ANALOG/VOLTAGE NON-CONTACT SENSOR (OUPUTS V1, V2, I1)

FOR ZERO/HOME POSITION CAPABILITY WITH ALL ANALOG ABSOLUTE NON-CONTACT POSITION SENSORS

DT04-4P MALE DT04-4P J1939 OUTPUT FACE VIEW 1 - VEI - CAN HIGH



1 = YEL = CAN HIGH 2 = GRN = CAN LOW 3 = RED = +VDC (VIN)

4 = BLK = COMMON/GROUND

M12-5P MALE FACE VIEW



M12-5P/CABLE/FLYING LEAD QUADRATURE OUTPUT

1 = BRN = +VDC (VIN) 2 = WHT = CHANNEL B

3 = BLUE = COMMON/GROUND 4 = BLK = CHANNEL A 5 = GRY = CHANNEL Z

M12-5P AND 5 CONDUCTOR CABLE J1939 OUTPUT

1 = BRN = +VDC (VIN) 2 = WHT = CAN HIGH

3 = BLUE = COMMON/GROUND 4 = BLK = CAN LOW

5 = GRY = OPTIONAL ADDRESS PROGRAMMING RESISTOR

DT04-6P MALE FACE VIEW

2 = 1 3 = 2 4 =

DT04-6P J1939 OUTPUT1 = YEL = CAN HIGH

2 = GRN = CAN LOW

3 = RED = +VDC (VIN)

4 = BLK = ADDRESS GROUND 5 = WHT = ADDRESS PROG. RESISTOR 6 = BLK = COMMON/GROUND

Dimensions informative only

For most recent dimensions please consult factory

M12-5P/CABLE/FLYING LEAD PROPORTIONAL (ANALOG) OUTPUT

1 = BRN = +VDC (VIN) 2 = WHT = DIG. LIMIT OUT* 3 = BLUE = COMMON/GROUND 4 = BLK = PROP. VDC OUTPUT 5 = GRY = NOT USED *OPTION CONSULT FACTORY



HP58 Hockey Puck™ non-contact rotary position sensor

- Patented true non-contact position sensing
 - 0.5" (12mm) gap between sensor and application
 - 0.10" (2.5mm) center alignment
 - 30° planar tilt
- Totally sealed IP69K (connector dependent)
- LED indicators for power and output feedback
- Incremental or Absolute position
- Outputs: Quadrature, Step and Direction, SSI, PWM, Analog, Modicon MODBUS, & J1939 Can Bus
- Detects rotation through non-ferrous barriers; Special applications include use in explosion proof housings, high PSI zone separation, and enclosed rotational measurement



STANDARD OPER	ATING CH	ARACTERIS	TICS
ELECTRICAL	Outputs		Incremental 13 bit Quadrature w/ Single Ended Output A B Z
ELECTRICAL		A - [PPR] - DIPP	Incremental 13 bit Quadrature w/ Differential Output A B Z & A' B' Z'
		A - 1939	J1939 13 bit @ 1000 positions (8192 positions max)
		A - MOD1	Modicon MODBUS @ 8192 positions
		B - PWM	PWM absolute position
		A - SSI1	SSI absolute position @ 8192 positions
		V1	Voltage Out / 5 VDC IN, 0-5 VDC OUT (code V3 for 2x redundant output)
		V2	Voltage Out / 6-36 VDC IN, 0-5 VDC OUT
		I1	Current Out / 0-24 VDC IN, 4-20 mA OUT (code I1 for 2x redundant output)
	Input Power	r	6 to 30 VDC at approx 60 mA max, not including output loads
	Electrical Pr	otection	Over-voltage, reserve-voltage, output short-circuit protected
	LED Indicate	ors	Power and output channels
	Connection	s	Terminal Plug, M8, M12, M12 Pigtail, Flying Lead Cable, Shielded Flying Lead, or Deutsch - 4 or 6 pin
	Resolution		0.3°
Repeatability			0.30%
	Nonlinearit	у	<1%
MECHANICAL	Housing Dia	ameter	58mm
MECHANICAL	Housing Ma	iterial	HP58 Black Delrin™ (standard) or White Delrin™; HP58SE Red Aluminum
	Housing He	ight	0.75" (19mm) body; 1.5" (38.1mm) w/ M12 connector
	Mounting		60.128 mounting holes
***	Weight		2.6 oz
* Non-contact tolerances rated using MAGH-RING	Magnet / se		Standard 0.5" (12mm) (Max w/ custom mag assembly up to 1" [30mm])
1/4x20 magnet accessory.		er tilt / axial gap*	Planar 30° (Max 45°) / Axial 0.1" (2.5mm) (Max 0.16" [4mm])
17-1×20 Magnet accessory.	Speed		3000 RPM max
ENVIRONMENTAL	Operating Temperature		-30° to +80° C
ENVIRONMENTAL	Storage Ten	nperature	-40° to +90° C
	Humidity		100%
	Shock		400g/6ms (MIL STD 202)
	Vibration		5 to 3000 Hz, 20g (MIL STD 202)
	Protection (Class	IP69K (connection dependent)

General ordering guide found on next page (S2; I5/2)



Hockey Puck™ Non-contact rotary position sensor HP58 General Ordering Guide Non-contact; HP58 / 2 of 4

NON-CONTACT POSITION SENSORS

HP58 GENERAL ORDERING GUIDE

Build part number first by selecting **Housing Style** (code 1), **MagElec** (code 2), and **Connection** (code 3). Add **Special Codes** (code 4) to the end of the Joral part number. Refer to **'Special Part Number Information'** for explanation of modifiers.

Examples: HP58-A-0080-SEPP-SC72-31 - Black Delrin™ (HP58), Side exit (31), 72" shielded cable (SC72), 13 bit incremental quadrature @ 80 PPR

HP58-A-1939-M12-90 - Black Delrin™ (HP58), Back exit (standard), M12 connector (M12), J1939 @ 8192 positions (modifier 90 for 8192)

HP58SE-V1-0-180-0.5-4.5-CW-C72-31 - Red Aluminum (HP58SE), Side exit (31), 0-5v Out (V1) @ 0-180°, 0.5-4.5v out, clockwise signal

Code 1: Housing Style	Code 2: MagElec (Sensor Output)		Code 3: Connection		Code 4: Special Codes	
HP58	A SEPP		TRM	Pluggable Terminal block	31	Side (housing wall)
HP58 material Black Delrin™,		quadrature - A B Z	INS	Wire insertion terminal	32	Front (magnet side)
connector orientation BACK EXIT standard. To designate SIDE EXIT	A DIPP	13 bit differential	M8	M8 male	33	Back (epoxy side)
connection use special code 31.		quadrature - A B Z, A' B' Z'	M12	M12 male	50	White Delrin
(Side exit for HP58 CABLE ONLY)	A - 1939	13 bit J1939	M12P	M12 male on 18' pigtail	51	Red Aluminum
	@ 1000 positions		CXX	Flying lead cable	71	Roller
	B - PWM	Absolute position PWM		(enter XX as inches)		Spindle
HP58SE HP58SE made out of Red Aluminum,	A - MOD1	13 bit Modicon MODBUS @8192 positions	SCXX	Shielded cable (enter XX as inches)	90	13 bit @ 8192 counts per rotation
connector orientation BACK EXIT	A - SSI1	Absolute position SSI	CSP	Cable with custom end		(Typical J1939 option)
standard. To designate SIDE EXIT		@ 8192 positions	DE4	DT04 - 4 pin male Deutsch	91	13 bit @ 1000 counts
connection use special code 31.	V1	5 VDC IN, 0-5 VDC OUT	DE6	DT04 - 6 pin male Deutsch		per rotation (Typical MODBUS option)
	V2	6-36 VDC IN, 0-5 VDC OUT				MODBOS option)
	V3	0-24 VDC IN, 4-20 mA OUT				
		x2 (Redundant output)				
* More outputs and connection	l1	0-24 VDC IN, 4-20 mA OUT				
options available, contact Joral if	I2	0-24 VDC IN, 4-20 mA OUT				
desired configuration is not listed		x2 (Redundant output)				

Special Part Number Information Review below code sections for important P/N build information

Code 1: Housing Style

- Modifier 31 For side exit connector on HP58 and HP58SE add 31 to end of Joral P/N
- HP58 Handles all back exit connections and CABLE ONLY side exit connections (M12P, CXX, SCXX, DE4 & DE6)
- HP58SE Handles ALL back and side exit connections (including M12 leaded side exit)

Code 2: MagElec

(A - _ _ - SEPP) or (A - _ _ - DIPP)

- Enter Quadrature PPR in place of ____
- A = 13 bit PPR
- Available 13 bit PPR: 0008, 0010, 0016, 0020, 0025, 0032, 0040, 0050, 0064, 0080, 0100, 0125, 0128, 0200, 0250, 0256, 0400, 0500, 1024, 2048

A - 1939

- Standard J1939 output is 1000 positions
- A = 13 bit
- MODIFIER 90 for 8192 positions (max resolution) add code 90 to end of HP58 P/N

A - MOD1

- Standard MOD1 output is 8192 positions
- A = 13 bit
- MODIFIER 91 for 1000 positions add code 90 to end of HP58 P/N

V1, V2, and I1 (Analog MagElec P/N Guide)

- First select MagElec code (V1, V2 or I1) then Angle Range (A1-A2), Voltage Range (VR1-VR2) and Signal Direction (Clockwise [CW] or Counter [CCW])
- PART NUMBER FORMULA (MagElec)-(A1-A2)-(VR1-VR2)-(CW or CCW)

• EXACT V1, V2, and I1 EXAMPLES

HP58 - V1 - 0-360 - 0.5-4.5 - CW - C72 HP58 - V2 - 0-180 - 0-5 - CCW - DE4 HP58 - I1 - 180-270 - 4-20 - CW - M12

Code 3: Connections

- All Outputs, All Connections Connector exit standard is BACK EXIT (sensor epoxy side) for housing HP58 and HP58SE (for SIDE EXIT use modifier 31)
- **J1939 Output** Addressing via varying value resistor in connection requires at least five conductors (M12, DE6 and Cables addressing compatible)
- All Outputs w/ Deutsch DE4 and DE6 connection Deutsch connectors add \$20 to HP58 list

Hockey Puck™

Non-contact rotary position sensor **HP58 Dimensions & General Pin-outs**

Non-contact; HP58 / 3 of 4

OPTIONAL CABLE SIDE OUTLET CABLE WITH FLYING LEADS OR CABLE WITH MU2-5

NON-CONTACT POSITION SENSORS

HP58 DIMENSIONS & GENERAL PIN OUTS DIMENSIONS 1 OF 2

MAGNET NOTE:

STANDARD MAGNET INCLUDED AS ACCESSORY WITH PURCHASE OF NON-CONTACT SENSOR

STANDARD MAGNET MAG-H-RING-ASSM. 1/4-20 X ,47



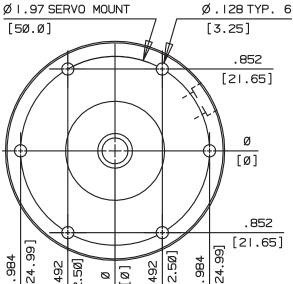
HOUSING/INSTALL NOTES:

MAGNET MOUNT MATERIALS MUST HAVE Ø1.0 [25.4] HOLE CENTERED ON SENSOR CENTERLINE

NON-MAGNETIC MOUNT MATERIAL, MAY BE SOLID

MOUNT WITH 316 STAINLESS STEEL 4-40 SCREWS

SENSOR FACE



M12-5P/CABLE/FLYING LEAD

2 = WHT = DIG. LIMIT OUT*

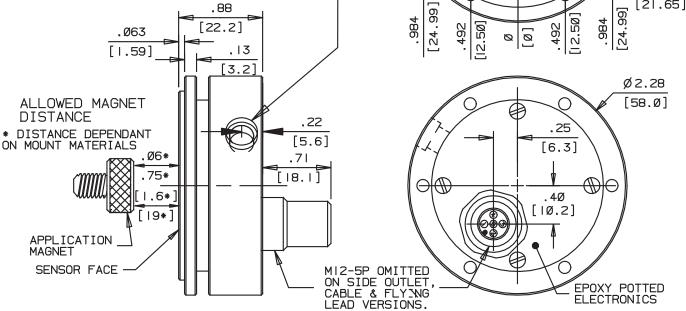
*OPTION CONSULT FACTORY

3 = BLUE = COMMON/GROUND

4 = BLK = PROP. VDC OUTPUT 5 = GRY = NOT USED

1 = BRN = +VDC(VIN)

PROPORTIONAL (ANALOG) OUTPUT



DT04-4P MALE **FACE VIEW**

DT04-4P J1939 OUTPUT



= YEL = CAN HIGH = GRN = CAN LOW = +VDC (VIN) 3 RED = BLK = COMMON/GROUND

DT04-6P MALE **FACE VIEW**

DT04-6P J1939 OUTPUT

1 = YEL = CAN HIGH GRN = CAN LOW = 3 = RFD = +VDC (VIN) = BIK

4 = ADDRESS GROUND = WHT = ADDRESS PROG. RESISTOR 5 = COMMON/GROUND BLK

M12-5P MALE **FACE VIEW**



M12-5P/CABLE/FLYING LEAD QUADRATURE OUTPUT

= BRN = +VDC (VIN) 2 = WHT = CHANNEL B 3

= BLUE = COMMON/GROUND 4 = BLK = CHANNEL A = GRY = CHANNEL Z

M12-5P AND 5 CONDUCTOR **CABLE J1939 OUTPUT**

1 = BRN = +VDC(VIN)2 = WHT = CAN HIGH

3 = BLUE = COMMON/GROUND

OPTIONAL ADDRESS 5 = GRY

4 = BLK = CAN LOW

PROGRAMMING RESISTOR

Dimensions informative only For most recent dimensions please consult factory

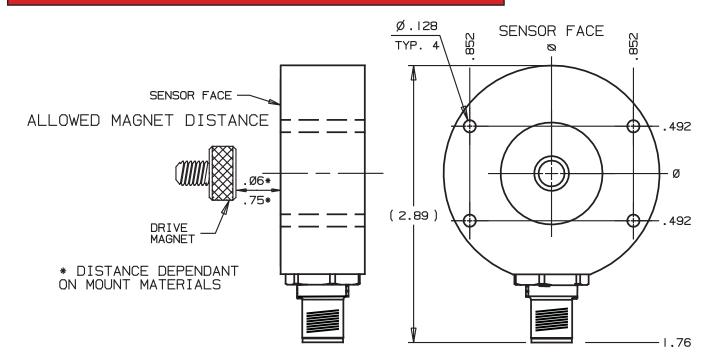
Hockey Puck™

Non-contact rotary position sensor HP58 Dimensions & General Pin-outs

Non-contact; HP58SE / 4 of 4

NON-CONTACT POSITION SENSORS

HP58SE DIMENSIONS & GENERAL PIN OUTS DIMENSIONS 2 OF 2



MAGNET NOTE:

STANDARD MAGNET INCLUDED AS ACCESSORY WITH PURCHASE OF NON-CONTACT SENSOR

STANDARD MAGNET MAG-H-RING-ASSM. T 1/4-20 X .47



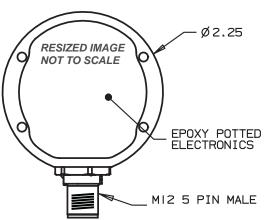


HOUSING/INSTALL NOTES:

MAGNET MOUNT MATERIALS MUST HAVE Ø1.0 [25.4] HOLE CENTERED ON SENSOR CENTERLINE

NON-MAGNETIC MOUNT MATERIAL, MAY BE SOLID

MOUNT WITH 316 STAINLESS STEEL 4-40 SCREWS



DT04-4P MALE

DT04-4P J1939 OUTPUT



1 = YEL = CAN HIGH 2 = GRN = CAN LOW 3 = RED = +VDC (VIN) 4 = BLK = COMMON/GROUND

DT04-6P MALE

DT04-6P J1939 OUTPUT1 = YEL = CAN HIGH



2 = GRN = CAN LOW 3 = RED = +VDC (VIN) 4 = BLK = ADDRESS GROUND 5 = WHT = ADDRESS PROG. RESISTOR 6 = BLK = COMMON/GROUND

M12-5P MALE FACE VIEW

M12-5P/CABLE/FLYING LEAD QUADRATURE OUTPUT



1 = BRN = +VDC (VIN) 2 = WHT = CHANNEL B 3 = BLUE = COMMON/GROUND 4 = BLK = CHANNEL A 5 = GRY = CHANNEL Z

M12-5P AND 5 CONDUCTOR CABLE J1939 OUTPUT

1 = BRN = +VDC (VIN) 2 = WHT = CAN HIGH

3 = BLUE = COMMON/GROUND 4 = BLK = CAN LOW

5 = GRY = OPTIONAL ADDRESS PROGRAMMING RESISTOR

Dimensions informative only For most recent dimensions please consult factory

M12-5P/CABLE/FLYING LEAD PROPORTIONAL (ANALOG) OUTPUT

